

# Continuity and Differentiability, Methods of Differentiation

## Properties of Continuous Functions

Here we present two extremely useful properties of continuous functions;

Let  $y = f(x)$  be a continuous function  $\forall x \in [a, b]$ , then following results hold true.

- (i)  $f$  is bounded between  $a$  and  $b$ . This simply means that we can find real numbers  $m_1$  and  $m_2$  such  $m_1 \leq f(x) \leq m_2 \forall x \in [a, b]$ .
- (ii) Every value between  $f(a)$  and  $f(b)$  will be assumed by the function atleast once. This property is called intermediate value theorem of continuous function.

In particular if  $f(a) \cdot f(b) < 0$ , then  $f(x)$  will become zero atleast once in  $(a, b)$ . It also means that if  $f(a)$  and  $f(b)$  have opposite signs then the equation  $f(x) = 0$  will have atleast one real root in  $(a, b)$ .

## Types of Discontinuities

### Type-1 : (Removable type of discontinuities)

- (a) **Missing point discontinuity:** Where  $\lim_{x \rightarrow a} f(x)$  exists finitely but  $f(a)$  is not defined.
- (b) **Isolated point discontinuity :** Where  $\lim_{x \rightarrow a} f(x)$  exists &  $f(a)$  also exists but;  $\lim_{x \rightarrow a} f(x) \neq f(a)$ .

### Type-2 : (Non-Removable type of discontinuities)

- (a) **Finite type discontinuity :** In such type of discontinuity left hand limit and right hand limit at a point exists but are not equal.
- (b) **Infinite type discontinuity :** In such type of discontinuity atleast one of the limit viz. LHL and RHL is tending to infinity.
- (c) **Oscillatory type discontinuity :** Limits oscillate between two finite quantities.

## Derivability of Function at a Point

If  $f'(a^+) = f'(a^-) = \text{finite quantity}$ , then  $f(x)$  is said to be **derivable or differentiable at  $x = a$** . In such case  $f'(a^+) = f'(a^-) = f'(a)$  and it is called derivative or differential coefficient of  $f(x)$  at  $x = a$ .

Note:

- (i) All polynomial, trigonometric, inverse trigonometric, logarithmic and exponential function are continuous and differentiable in their domains, except at end points.
- (ii) If  $f(x)$  and  $g(x)$  are derivable at  $x = a$  then the functions  $f(x) + g(x)$ ,  $f(x) - g(x)$ ,  $f(x) \cdot g(x)$  will also be derivable at  $x = a$  and if  $g(a) \neq 0$  then the function  $f(x)/g(x)$  will also be derivable at  $x = a$ .

In short, for a function ' $f$ ':

**Differentiable  $\Rightarrow$  Continuous;**

**Not Differentiable  $\Rightarrow$  Not Continuous**

**But Not Continuous  $\Rightarrow$  Not Differentiable**

**Continuous  $\Rightarrow$  May or may not be Differentiable**

## Derivability Over an Interval

- (a)  $f(x)$  is said to be derivable over an open interval  $(a, b)$  if it is derivable at each and every point of the open interval  $(a, b)$ .
- (b)  $f(x)$  is said to be derivable over the closed interval  $[a, b]$  if:
  - (i)  $f(x)$  is derivable in  $(a, b)$  and
  - (ii) for the points  $a$  and  $b$ ,  $f'(a^+)$  &  $f'(b^-)$  exist.

Note:

- (i) If  $f(x)$  is differentiable at  $x = a$  and  $g(x)$  is not differentiable at  $x = a$ , then the product function  $F(x) = f(x) \cdot g(x)$  can still be differentiable at  $x = a$ .
- (ii) If  $f(x)$  &  $g(x)$  both are not differentiable at  $x = a$  then the product function;  $F(x) = f(x) \cdot g(x)$  can still be differentiable at  $x = a$ .
- (iii) If  $f(x)$  &  $g(x)$  both are non-derivable at  $x = a$  then the sum function  $F(x) = f(x) + g(x)$  may be a differentiable function.
- (iv) If  $f(x)$  is derivable at  $x = a$   $\nRightarrow$   $f'(x)$  is continuous at  $x = a$ .

## Differentiation of Some Elementary Functions

$$1. \frac{d}{dx}(x^n) = nx^{n-1}$$

$$2. \frac{d}{dx}(a^x) = a^x \ln a$$

$$3. \frac{d}{dx}(\ln |x|) = \frac{1}{x}$$

$$4. \frac{d}{dx}(\log_a x) = \frac{1}{x \ln a}$$

$$5. \frac{d}{dx}(\sin x) = \cos x$$

$$6. \frac{d}{dx}(\cos x) = -\sin x$$

$$7. \frac{d}{dx}(\sec x) = \sec x \tan x \quad 8. \frac{d}{dx}(\operatorname{cosec} x) = -\operatorname{cosec} x \cot x$$

$$9. \frac{d}{dx}(\tan x) = \sec^2 x \quad 10. \frac{d}{dx}(\cot x) = -\operatorname{cosec}^2 x$$

## Basic Theorems

$$1. \frac{d}{dx}(f \pm g)(x) = f'(x) \pm g'(x)$$

$$2. \frac{d}{dx}(k f(x)) = k \frac{d}{dx} f(x)$$

$$3. \frac{d}{dx}(f(x) \cdot g(x)) = f(x)g'(x) + g(x)f'(x)$$

$$4. \frac{d}{dx}\left(\frac{f(x)}{g(x)}\right) = \frac{g(x)f'(x) - f(x)g'(x)}{g^2(x)}$$

$$5. \frac{d}{dx}(f(g(x))) = f'(g(x))g'(x)$$

## Derivative of inverse Trigonometric Functions

$$\frac{d \sin^{-1} x}{dx} = \frac{1}{\sqrt{1-x^2}}, \quad \frac{d \cos^{-1} x}{dx} = -\frac{1}{\sqrt{1-x^2}}, \quad \text{for } -1 < x < 1.$$

$$\frac{d \tan^{-1} x}{dx} = \frac{1}{1+x^2}, \quad \frac{d \cot^{-1} x}{dx} = -\frac{1}{1+x^2} \quad (x \in \mathbb{R})$$

$$\frac{d \sec^{-1} x}{dx} = \frac{1}{|x|\sqrt{x^2-1}}, \quad \frac{d \operatorname{cosec}^{-1} x}{dx} = -\frac{1}{|x|\sqrt{x^2-1}}, \quad \text{for } x \in (-\infty, -1) \cup (1, \infty)$$

## Differentiation Using Substitution

Following substitutions are normally used to simplify these expression.

1.  $\sqrt{x^2 + a^2}$  by substituting  $x = a \tan \theta$ , where  $-\frac{\pi}{2} < \theta < \frac{\pi}{2}$
2.  $\sqrt{a^2 - x^2}$  by substituting  $x = a \sin \theta$ , where  $-\frac{\pi}{2} \leq \theta \leq \frac{\pi}{2}$
3.  $\sqrt{x^2 - a^2}$  by substituting  $x = a \sec \theta$ , where  $\theta \in [0, \pi]$ ,  $\theta \neq \frac{\pi}{2}$
4.  $\sqrt{\frac{x+a}{a-x}}$  by substituting  $x = a \cos \theta$ , where  $\theta \in [0, \pi]$ .

## Parametric Differentiation

If  $y = f(\theta)$  and  $x = g(\theta)$  where  $\theta$  is a parameter, then  $\frac{dy}{dx} = \frac{dy/d\theta}{dx/d\theta}$ .

## Derivative of one Function with Respect to Another

Let  $y = f(x)$ ;  $z = g(x)$  then  $\frac{dy}{dz} = \frac{dy/dx}{dz/dx} = \frac{f'(x)}{g'(x)}$ .

$$\diamond \text{ If } F(x) = \begin{vmatrix} f(x) & g(x) & h(x) \\ l(x) & m(x) & n(x) \\ u(x) & v(x) & w(x) \end{vmatrix}, \text{ where } f, g, h, l, m, n, u, v, w$$

are differentiable functions of  $x$  then

$$F'(x) = \begin{vmatrix} f'(x) & g'(x) & h'(x) \\ l(x) & m(x) & n(x) \\ u(x) & v(x) & w(x) \end{vmatrix} + \begin{vmatrix} f(x) & g(x) & h(x) \\ l'(x) & m'(x) & n'(x) \\ u(x) & v(x) & w(x) \end{vmatrix} + \begin{vmatrix} f(x) & g(x) & h(x) \\ l(x) & m(x) & n(x) \\ u'(x) & v'(x) & w'(x) \end{vmatrix}$$